

Fronts with a growth cutoff but with speed higher than the linear spreading speed

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Fronts, propagating into an unstable state $\phi=0$, whose asymptotic speed v_{as} is equal to the linear spreading speed v^* of infinitesimal perturbations about that state (so-called pulled fronts), are very sensitive to changes in the growth rate $f(\phi)$ for $\phi \ll 1$. It was recently found that with a small cutoff, $f(\phi)=0$ for $\phi < \varepsilon$, v_{as} converges to v^* very slowly from below, as $\ln^{-2} \varepsilon$. Here we show that with such a cutoff *and* a small enhancement of the growth rate for small ϕ behind it, one can have $v_{as} > v^*$, *even* in the limit $\varepsilon \rightarrow 0$. The effect is confirmed in a stochastic lattice model simulation where the growth rules for a few particles per site are accordingly modified.

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Pulled fronts are those fronts that propagate into a linearly unstable state, and whose asymptotic front speed v_{as} equals the linear spreading speed v^* of infinitesimal perturbations about the unstable state [1–3]. The name pulled front refers to the picture that in the leading edge of these fronts, the perturbation about the unstable state grows and spreads with speed v^* , while the rest of the front gets “pulled along” by the leading edge. That this notion is not merely an intuitive picture but can be turned into a mathematically precise analysis is illustrated by the recent derivation of exact results for the general power law convergence of the front speed to the asymptotic value v^* [3]. Fronts that propagate into a linearly unstable state and whose asymptotic speed $v_{as} > v^*$ are referred to as pushed, as it is the nonlinear growth in the region behind the leading edge that pushes their front speed to higher values. If the state is not linearly unstable, then v^* is trivially zero; in such cases the front propagation is always dominated by the nonlinear growth in the front region itself, and hence fronts in this case are in a sense “pushed” too.

For the field $\phi(x,t)$, the dynamics of fronts that we consider in this paper is given by the usual nonlinear diffusion equation

$$\frac{\partial \phi}{\partial t} = \frac{\partial^2 \phi}{\partial x^2} + f(\phi). \quad (1)$$

In the standard case, the growth function $f(\phi)$ has the form $f(\phi) = \phi - \phi^n$, with $n > 1$. Equation (1) has two stationary states for $\phi(x,t)$: $\phi(x,t) = 0$ and $\phi(x,t) = 1$. Of these, $\phi(x,t) = 1$ is stable and $\phi(x,t) = 0$ is unstable. The asymptotic speed of (pulled) fronts propagating from $\phi(x,t) = 1$ into $\phi(x,t) = 0$ in Eq. (1) is $v^* = 2$.

The sensitivity of pulled fronts to the precise dynamics for small perturbations about the unstable state has recently surfaced in a remarkable way [4]. Often, in equations like Eq. (1), the field $\phi(x,t)$ is the density of particles in a continuum description. If one then considers fronts in stochastic particle model versions of Eq. (1), the linear growth term in $f(\phi)$ implies that for small particle density, the rate at which new particles are created is proportional to the density itself. Brunet and Derrida [4] were the first to realize the fact that for new particles to be created in any given realization, the

density must be at least one “quantum” of particle density strong, and that this provides a natural lower cutoff for the growth that strongly affects the front speed. Indeed, to mimic this effect, they considered a deterministic front of the type in Eq. (1) with $n = 3$, and by hand introduced a cutoff of the type sketched in Fig. 1(a) in the growth function at $\phi = \varepsilon \ll 1$. In this paper, we denote their growth function by $f(\phi, \varepsilon) \equiv [\phi - \phi^3] \Theta(\phi - \varepsilon)$, where Θ is the unit step function. For small ε , the asymptotic front speed $v_{as}(\varepsilon)$ was then found to be [4]

$$v_{as}(\varepsilon) \approx v^* - \frac{\pi^2}{(\ln \varepsilon)^2} + \dots \quad (2)$$

Brunet and Derrida subsequently identified ε with $1/N$, where N is the average number of particles at the saturation state of the front, corresponding to the stable state $\phi(x,t) = 1$ of the density field. The slow logarithmic convergence to the asymptotic front speed from below as a function of N , implied by Eq. (2), has been confirmed in various studies of stochastic lattice models [4–9]. Note that for $\phi < \varepsilon$, the growth function f vanishes, and as a result, strictly speaking,

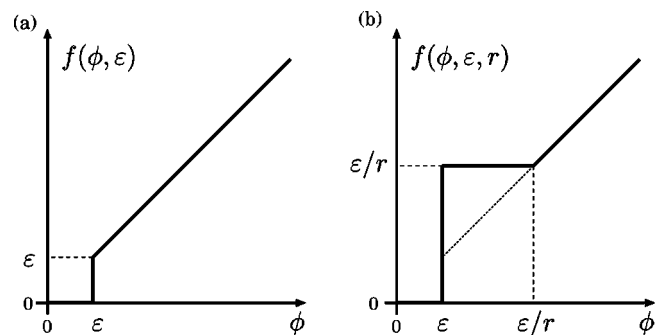


FIG. 1. (a) Shape of the function $f(\phi, \varepsilon)$ used by Brunet and Derrida to study the effect of a finite particle cutoff in the growth rate on the front speed. (b) The growth function $f(\phi, \varepsilon, r)$ (thick line) we analyze in this paper. In both cases we have kept only the linear term of $f(\phi)$ to plot the graphs, since $\varepsilon \ll 1$, so that the nonlinear terms in f are much smaller than the linear terms.

the state $\phi=0$ is not linearly unstable; hence fronts in this model are always weakly pushed for any nonzero value of ε [10].

In this paper, we demonstrate an even more surprising aspect of the sensitivity to small changes in the growth function f of the “pulled” fronts that we have at $\varepsilon=0$: if f is sufficiently *enhanced* in a range of ϕ of the order of ε , the asymptotic front speed v_{as} can become larger than v^* and *not converge to v^* as $\varepsilon \rightarrow 0$* . For fluctuating fronts, this implies that if the stochastic growth rates for small occupation densities n_i are somewhat enhanced over a linear behavior $\sim n_i$, then such stochastic fronts may move faster than v^* and *never converge to their naive mean field limit for $N \rightarrow \infty$* . This effect may be of relevance for the coarse-grained field theory for diffusion-limited aggregation, as it is empirically known to be essential to modify the growth function for small cluster densities [11].

We now discuss our results first, and then summarize their derivation.

To be specific, we consider the nonlinear diffusion equation (1) with the growth function sketched in Fig. 1(b),

$$\begin{aligned} f(\phi, \varepsilon, r) &= f(\phi, \varepsilon) \quad \text{for } \phi < \varepsilon \text{ and} \\ &= \varepsilon/r \quad \text{for } \varepsilon \leq \phi \leq \varepsilon/r, \end{aligned} \quad (3)$$

with $r < 1$. We show that while for any fixed value of r

$$\lim_{\varepsilon \rightarrow 0} f(\phi, \varepsilon, r) = f(\phi), \quad (4)$$

the asymptotic front speed $v_{\text{as}}(\varepsilon, r)$ has the property that

$$\begin{aligned} \lim_{\varepsilon \rightarrow 0} v_{\text{as}}(\varepsilon, r) &= v^* \quad \text{for } r > r_c, \\ \lim_{\varepsilon \rightarrow 0} v_{\text{as}}(\varepsilon, r) &> v^* \quad \text{for } r < r_c, \end{aligned} \quad (5)$$

where

$$r_c = \frac{1 + e^{-(v^*)^2 - 2}}{v^*{}^2} = 0.283\,833 \dots \quad (6)$$

Hereafter, for simplicity, we denote $v_{\text{as}}(\varepsilon, r)$ simply by v . For $\varepsilon \rightarrow 0$, the asymptotic speed at a given value of $r \leq r_c$ in our model is given by the relation

$$\begin{aligned} r &= \frac{1}{v^2} \left[1 + \frac{1 - \frac{2}{v} \sqrt{\frac{v^2}{4} - 1}}{1 + \frac{2}{v} \sqrt{\frac{v^2}{4} - 1}} \right] \\ &\times \exp \left(- \left\{ v^2 - \frac{2}{1 + \frac{2}{v} \sqrt{\frac{v^2}{4} - 1}} \right\} \right), \end{aligned} \quad (7)$$

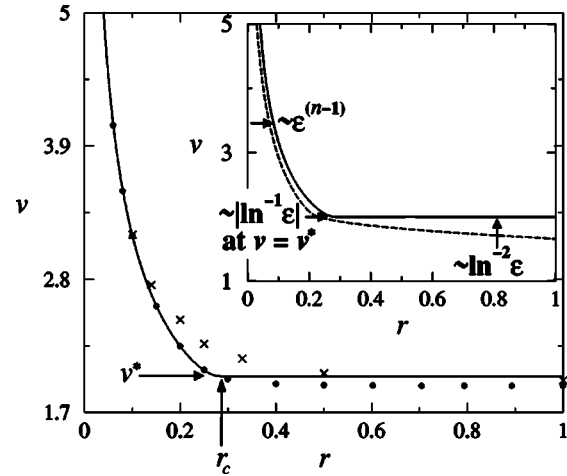


FIG. 2. Comparison of simulation data for $v_{\text{as}}(\varepsilon, r)$ with the analytical prediction (7), which is plotted as the solid line. The solid dots represent the numerical data for Eq. (3) with $\varepsilon = 2 \times 10^{-5}$ and $n = 3$. The crosses are the data points for fronts in the stochastic growth model described in the text. Inset: illustration of the leading order rate of convergence of the $v_{\text{as}}(\varepsilon, r)$ curve to the $\varepsilon \rightarrow 0$ limit, by means of the schematic dashed curve.

from which the value of r_c , given by Eq. (6), follows.

These expressions show that the limits do not commute for $r < r_c$: taking the limit $\varepsilon \rightarrow 0$ first in f yields a front speed v^* but the limit $v_{\text{as}}(\varepsilon \rightarrow 0, r) > v^*$. The reason is that for $r < r_c$ there is always a little tail of the front that runs faster than v^* and makes ϕ nonzero. Once ϕ is nonzero, growth continues and the region behind it just has to follow it with the same asymptotic speed.

Our analysis is corroborated by numerical results obtained by solving Eq. (1) forward in time, (with Gaussian initial conditions). The data for v vs r at $\varepsilon = 2 \times 10^{-5}$ are shown as solid dots in Fig. 2. Note that for $r < r_c$, the solid dots fall on top of our prediction (7) drawn with a solid line, while for $r > r_c$, they systematically fall below the solid line $v = v^*$. The reason for it is the difference between the rates of convergence as $\varepsilon \rightarrow 0$, which is illustrated in the inset of Fig. 2 by means of the schematically drawn dashed line. The arrows in the inset indicate the rate of convergence of the dashed r - v curve towards the limiting one, given by Eq. (7). For $r > r_c$, the convergence is $\sim \ln^{-2} \varepsilon$ as in the case for $r = 1$, analyzed in Ref. [4]; but for $r < r_c$ the convergence is much faster, ε^{n-1} . This latter behavior is illustrated for $r = 0.2$ and $n = 2, 3$ in Fig. 3—note the fine scale on the vertical axis.

The fact that the effect of increasing asymptotic speed with decreasing r below r_c is a *real* effect for stochastic fronts too is illustrated by the crosses in Fig. 2: these represent the data for the average speed of fronts in a reaction-diffusion system $X \rightleftharpoons 2X$, for discrete X particles on a lattice with $N = 10^4$ [12], where the growth rates have been modified when the number of particles n_i on a lattice site i is less than $1/r$. In accord with the shape of the growth function f illustrated in Fig. 1(b), the rate at which particles are created at a lattice site i with $1 \leq n_i < 1/r$ particles is simply taken to be the same as the rate for $n_i = 1/r$ (corresponding to the

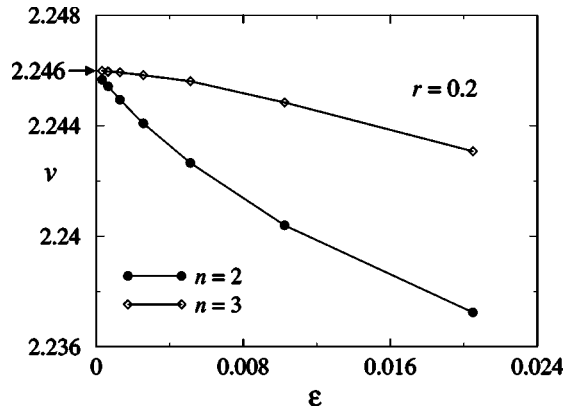


FIG. 3. Numerical data for $v_{\text{as}}(\varepsilon, r)$ as a function of ε for $n = 2$ and 3 , at $r = 0.2$. The graph demonstrates the insensitivity of v to ε for small values of ε (note the fine scale on the vertical axis), as well as the convergence as ε^{n-1} to its $\varepsilon \rightarrow 0$ value ≈ 2.246 , given by Eq. (7), for two different values of n .

integral values $1/r = 1, 2, 3, 4, 5, 7$, and 10 , due to the discreteness of particles). As one can see from Fig. 2, already when $r = 0.5$, i.e., when only the growth rate at lattice sites with one particle is increased by a factor 2, the asymptotic growth speed is above the value $v^* = 2$.

In the remainder of this paper, we derive the analytical results for the nonlinear diffusion equation with the growth function (3). Our analysis is based on the following observation: for $\varepsilon = 0$, it is well known that the nonlinear diffusion equation allows a continuous family of front solutions with $v \geq v^*$. When such front solutions are parametrized by their velocity v , and when the growth rate is modified to allow a transition to a “pushed” front with velocity v^\dagger , it is also known [2,3] that solutions with $v < v^\dagger$ are unstable to a localized mode. In our analysis, we therefore consider a front with a given fixed velocity v and, for small ε , determine when upon decreasing r a localized mode of the stability operator crosses the eigenvalue zero. In the limit $\varepsilon \rightarrow 0$ this marks the selected pushed front in the r - v diagram.

To carry out the linear stability analysis of the front solution, it is convenient to follow the standard route of transforming the linear eigenvalue equation into a Schrödinger eigenvalue problem [1,3]. We consider a function $\phi(x, t)$, which is infinitesimally different from the asymptotic front solution $\phi_{\text{as}}(\xi)$ in the comoving frame $\xi = x - vt$, i.e., $\phi(x, t) = \phi_{\text{as}}(\xi) + \eta(\xi, t)$. Upon linearizing Eq. (1) in the comoving frame, one finds that the function $\eta(\xi, t)$ obeys the following equation:

$$\frac{\partial \eta}{\partial t} = v \frac{\partial \eta}{\partial \xi} + \frac{\partial^2 \eta}{\partial \xi^2} + \left. \frac{\delta f(\phi)}{\delta \phi} \right|_{\phi = \phi_{\text{as}}} \eta. \quad (8)$$

Since this equation is linear in η , the question of stability can be answered by studying the spectrum of the temporal eigenvalues. To this end, we express $\eta(\xi, t)$ as

$$\eta(\xi, t) = e^{-Et} e^{-v\xi/2} \psi_E(\xi), \quad (9)$$

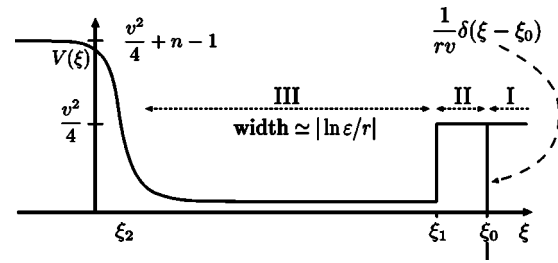


FIG. 4. The potential $V(\xi)$ for $v \geq v^*$ and infinitesimally small ε in the Schrödinger operator that determines the temporal eigenvalues of the stability analysis. ξ_2 marks the position of the region of finite width where the potential crosses over from the asymptotic value on the left where $\phi_{\text{as}} \approx 1$ to the value in the well where $\phi_{\text{as}} \ll 1$, ξ_1 the position of the step and ξ_0 the position of the δ -function term in the potential.

which converts Eq. (8) to a one-dimensional Schrödinger equation for a particle in a potential with $\hbar^2/2m = 1$,

$$\left[-\frac{d^2}{d\xi^2} + \frac{v^2}{4} - \left. \frac{\delta f(\phi)}{\delta \phi} \right|_{\phi = \phi_{\text{as}}} \right] \psi_E(\xi) = E \psi_E(\xi). \quad (10)$$

In Eq. (10), the quantity

$$V(\xi) = \left[\frac{v^2}{4} - \left. \frac{\delta f(\phi)}{\delta \phi} \right|_{\phi = \phi_{\text{as}}} \right]$$

plays the role of the potential. It is easily obtained explicitly from the expression (3) for $f(\phi, \varepsilon, r)$ as

$$V(\xi) = \left[\frac{v^2}{4} - 1 + n \phi_{\text{as}}^{n-1}(\xi) \right] \Theta(\xi_1 - \xi) + \frac{v^2}{4} \Theta(\xi - \xi_1) - \frac{1}{rv} \delta(\xi - \xi_0), \quad (11)$$

where $\phi(\xi_0) = \varepsilon$ and $\phi(\xi_1) = \varepsilon/r$. The form of the potential for $v > v^*$ and small ε is sketched in Fig. 4. Keep in mind that $\phi_{\text{as}}(\xi)$ is a monotonically increasing function from ε/r at ξ_1 towards the left, and that $\phi_{\text{as}}(\xi \rightarrow -\infty) = 1$. As a result, in Fig. 4, $V(\xi)$ also increases monotonically towards the left for $\xi < \xi_1$. On the right of ξ_1 , $V(\xi)$ is constant at $v^2/4$, and at ξ_0 , there is an attractive δ -function potential of strength $(rv)^{-1}$ [13]. The crucial feature for the stability analysis below is the fact that $V(\xi)$ stays remarkably flat at a value $2\varepsilon/r$ over a distance $(\xi_1 - \xi_2) \approx |\ln \varepsilon/r|$ [10], and on the left of ξ_2 , it increases to the value of $v^2/4 + n - 1$, over a distance of order unity.

If there exist negative eigenvalues of the Schrödinger equation (10), then according to Eq. (9), $\eta(\xi, t)$ grows in time in the comoving frame, i.e., the front solution $\phi_{\text{as}}(\xi)$ is unstable. For our purpose, therefore, we look for the value of r at which there is a bound state of Eq. (10) with eigenvalue E , such that $E \rightarrow 0^-$ for the potential sketched in Fig. 4. This is a problem in elementary quantum mechanics. For $\varepsilon \rightarrow 0$,

the potential $V(\xi)$ is essentially constant in the left neighborhood of ξ_1 , and hence for $v > v^*$ and $E \rightarrow 0^-$, $\psi_E(\xi)$ can be written as

$$\begin{aligned}\psi_E(\xi) &= A_- e^{\lambda_1(\xi - \xi_1)} && \text{for } \xi \leq \xi_1, \\ &= A e^{\lambda_2(\xi - \xi_0)} + B e^{\lambda_2(\xi_0 - \xi)} && \text{for } \xi_1 \leq \xi \leq \xi_0, \\ &= A_2 e^{-\lambda_2(\xi - \xi_0)} && \text{for } \xi > \xi_0,\end{aligned}\quad (12)$$

where $\lambda_1 = \sqrt{v^2/4 - 1}$ and $\lambda_2 = v/2$. The function $\psi_E(\xi)$ must be continuous at ξ_1 and ξ_0 , while its slope is continuous at ξ_1 , but not at ξ_0 . Matching of these boundary conditions to determine the value of r , where the bound state eigenvalue E crosses zero, also requires an expression for the distance $\xi_0 - \xi_1$. To this end, we divide the range of ϕ values between 0 and 1 into the three regions marked in Fig. 4: (i) region I, where $\phi_{\text{as}} < \varepsilon$, (ii) region II, where $\varepsilon \leq \phi_{\text{as}} < \varepsilon/r$, and (iii) region III, where $\phi_{\text{as}} \geq \varepsilon/r$. In the comoving frame, the asymptotic shape $\phi_{\text{as}}(\xi)$ of the front is the solution of the differential equation $\phi_{\text{as}}'' + v \phi_{\text{as}}' + f(\phi_{\text{as}}, \varepsilon, r) = 0$, where a prime denotes a derivative with respect to ξ . The solutions of $\phi_{\text{as}}(\xi)$ in the regions I and II that satisfy the continuity of $\phi_{\text{as}}(\xi)$ and $\phi_{\text{as}}'(\xi)$ are, respectively, given by

$$\begin{aligned}\phi_{\text{as}}(\xi) &= \varepsilon e^{-v(\xi - \xi_0)} && \text{and} \\ \phi_{\text{as}}(\xi) &= \left[\varepsilon - \frac{\varepsilon}{rv^2} \right] e^{v(\xi_0 - \xi)} + \frac{\varepsilon(\xi_0 - \xi)}{rv} + \frac{\varepsilon}{rv^2}.\end{aligned}\quad (13)$$

The length $\xi_0 - \xi_1$ of region II is obtained by equating $\phi_{\text{as}}(\xi_1)$ from the second line of Eq. (13) to ε/r . After dividing out a factor of ε/r , this condition becomes

$$\left[r - \frac{1}{v^2} \right] e^{v(\xi_0 - \xi_1)} + \frac{\xi_0 - \xi_1}{v} + \frac{1}{v^2} = 1.\quad (14)$$

Thereafter, using Eqs. (12) and (13), one arrives at Eq. (7).

The above analysis yields the relation between v and the critical value of r in the limit $\varepsilon \rightarrow 0$. The convergence with ε , i.e., the rate of approach with ε of the dashed curve to the solid one in Fig. 2, can be obtained by considering the effect

of the $n\phi_{\text{as}}^{n-1}(\xi)$ term of $V(\xi)$ on the eigenfunctions and eigenvalues. For $v > v^*$, this term is simply a correction of order ε^{n-1} to the finite bottom value of the potential. This term can be included perturbatively, and accordingly it leads to a shift of order ε^{n-1} in the critical value of r . As Fig. 3 illustrates, this prediction is confirmed numerically. The case $v = v^*$ calls for a more detailed analysis, since the bottom value of the potential vanishes in the limit $\varepsilon \rightarrow 0$. In this case, it is known [3,4] that $\phi_{\text{as}}(\xi) \sim (C\xi + D)e^{-\xi}$, so $V(\xi) \approx n(\varepsilon/r)^{n-1}(\xi/\xi_1)^{n-1}e^{-(n-1)(\xi_1 - \xi)}$ in the leading order of ε . In dominant order, we need to keep only the exponential behavior, and the solution of $\psi_E(\xi)$ is then given by the Bessel function $A_- K_0(2\sqrt{n\varepsilon^{n-1}e^{-(n-1)(\xi_1 - \xi)}/r^{n-1}})$ in the left neighborhood of ξ_1 . The $|\ln^{-1}\varepsilon|$ scaling for the asymptotic approach of the dashed curve to the solid one is then easily obtained once the boundary conditions at ξ_1 and ξ_0 are matched using Eq. (14).

The logarithmic convergence of v to v^* from below for $r > r_c$ can be understood from an argument along the lines of that for $r = 1$ [4]. For $v < v^*$, the front profile $\phi_{\text{as}}(\xi)$ in region III is of the form $\phi_{\text{as}}(\xi) \sim C \sin[k(\xi - \xi_2) + \beta]e^{-\xi}$. For $r = 1$, region II is absent; in that case, the matching to the profile in region I and the divergence of the width $\xi_0 - \xi_2 \approx |\ln \varepsilon|$ implies $k \approx \pi |\ln \varepsilon|^{-1}$. For $r_c < r < 1$, the matching to region II will change the prefactor, but k will still scale as $|\ln \varepsilon|^{-1}$ because the width of region III still diverges logarithmically. As for $r_c \leq r < 1$, this translates into a scaling of $v^* - v$ as $|\ln \varepsilon|^{-2}$, with a prefactor that depends on r . Note that this scaling is nicely consistent with the convergence of the r - v curve towards the point (r_c, v^*) from the left, due to the fact that the slope of this curve vanishes at this point, and the convergence from below to this point scales as the square of the convergence from the left.

We finally end this paper with the note that if the (nonnegative) growth rate is bounded from above by $f(\phi, \varepsilon)$ in the interval $\phi \leq \varepsilon/r$, but is equal to $f(\phi, \varepsilon)$ for $\phi > \varepsilon/r$, then as $\varepsilon \rightarrow 0$, the asymptotic front speed converges to v^* with the *same* logarithmic convergence of Eq. (2) for *any* r . It simply follows from the inequality $v_{\text{as}}(\varepsilon/r) < v < v_{\text{as}}(\varepsilon)$, where $v_{\text{as}}(\varepsilon)$ is given by Eq. (2).

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- [12] This corresponds to $\tilde{\gamma} = 1$ and $N = 10^4$ for the model considered in Ref. [9].
- [13] The δ -function in Eq. (11) appears from the functional derivative of f in V , since there is a discontinuity of magnitude ε in $f(\phi_{\text{as}}, \varepsilon, r)$ at $\phi_{\text{as}} = \varepsilon$. This discontinuity contributes an amount equal to $\varepsilon r^{-1} d\Theta(\phi_{\text{as}} - \varepsilon)/d\phi_{\text{as}} = \varepsilon [r |\phi_{\text{as}}'(\xi_0)|]^{-1} \delta(\xi - \xi_0)$ to $V(\xi)$. As $\phi_{\text{as}}' = \varepsilon r$ according to Eq. (13), the prefactor $1/(rv)$.